

EUROPEAN CREDIT TRANSFER AND ACCUMULATION SYSTEM (ECTS) pl. M. Skłodowskiej-Curie 5, 60-965 Poznań

## **COURSE DESCRIPTION CARD - SYLLABUS**

Course name Robotization of production processes

#### Course

Field of study	Year/Semester
Management and production engineering	3/5
Area of study (specialization)	Profile of study
	general academ
Level of study	Course offered i
First-cycle studies	polish
Form of study	Requirements

full-time

# udy demic red in Requirements elective

## Number of hours

Lecture 15 Tutorials Laboratory classes 15 **Projects/seminars** 

Other (e.g. online)

#### Number of credit points

3

#### Lecturers

Responsible for the course/lecturer: PhD. Marcin Suszyński

Responsible for the course/lecturer:

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Faculty of Mechanical Engineering

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#### **Prerequisites**

The student should have knowledge of physics, mechanics and techniques at the secondary technical



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level. He should have the ability to solve elementary problems in the field of building control algorithms (programming rules) and designing technological processes based on his knowledge and the ability to obtain information from indicated sources.

## **Course objective**

Providing students with theoretical and practical issues related to the automation and robotization of production processes including basic manufacturing techniques in the scope specified by the program content appropriate for the field of study.

## **Course-related learning outcomes**

Knowledge The student is able to:

Identify, describe and explain the principle of operation of the basic structural units of the manipulator and the control system of an industrial robot.

Characterize the basic areas of application as well as the role and tasks of automation and robotization in typical technological processes.

Select appropriate programming instructions for a specific task in the field of programming industrial robots.

Skills

The student can:

Develop algorithms and control programs for cooperating industrial robots, taking into account the initial and final conditions, and carry out tests of the control program.

Identify a technical problem, determine its degree of complexity, and then propose a solution that takes into account the final goal (effect).

Social competences The student is able to:

Actively engage in solving the problems posed, independently develop and expand their competences, and cooperate in a team.

Properly define the priorities for the implementation of the task set by yourself or others.

Be entrepreneurial and creative (innovative).

## Methods for verifying learning outcomes and assessment criteria

Learning outcomes presented above are verified as follows:

The knowledge acquired during the course is verified on the attachment. It consists of 5 open-ended questions and one computational task with different scores. Passing threshold: 50%. The knowledge acquired during laboratory classes is verified on the basis of an oral or written answer regarding the content of each laboratory exercise performed, a report on each laboratory exercise according to the



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guidelines set out in the guide to exercises and indications of the laboratory teacher. In order to pass the laboratories, all exercises must be passed (positive grade from answers and reports).

### **Programme content**

#### Lecture

Development and forecasting in the robotics market; Application areas and robot classification; Mechanization, automation and robotization of production processes; Flexibility of production systems; Basic structure of industrial robots and manipulators; Advantages and disadvantages of automation and robotization of production processes; Technical and technological equipment of robotic stations (grippers, technological heads, cooperating devices); Examples of robotization of production processes including basic manufacturing techniques; New trends in the development of automation and robotization.

#### Lab

Practical exercises in the field of principles and methods of programming educational and industrial robots.

#### **Teaching methods**

Lecture: multimedia presentation illustrated with examples given on the board.

Laboratory exercises: performing experiments, solving problems, discussion, team work, programming.

#### **Bibliography**

Basic

Kost G., Łebkowski P., Węsierski Ł., Automatyzacja i robotyzacja procesów produkcyjnych, PWE,
2014

- 2. Żurek J., Podstawy Robotyzacji Laboratorium., WPP, Poznań, 2006
- 3. Zdanowicz R. Robotyzacja dyskretnych procesów produkcyjnych, WPŚ, Gliwice, 2011
- 4. Zdanowicz R, Robotyzacja procesów technologicznych, WPŚ, Gliwice, 2001
- 5. Podręczniki programowania robotów, IRp-6, Fanuc, Panasoni

#### Additional

- 1. Honczarenko J., Roboty przemysłowe. Budowa i Zastosowanie, WNT, Warszawa, 2010
- 2. Wrotny T., Robotyka i elastycznie zautomatyzowana produkcja, WNT, Warszawa, 1991

3. Marciniak M., Elementy automatyzacji we współczesnych procesach wytwarzania, WPW, Warszawa, 2007



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## Breakdown of average student's workload

	Hours	ECTS
Total workload	75	3,0
Classes requiring direct contact with the teacher	45	2,0
Student's own work (literature studies, preparation for	30	1,0
laboratory classes/tutorials, preparation for tests/exam, project		
preparation) <sup>1</sup>		

<sup>&</sup>lt;sup>1</sup> delete or add other activities as appropriate